



Temposonics

AN AMPHENOL COMPANY

Data Sheet

R-Series V RDV Analog

Magnetostrictive Linear Position Sensors

- Space-saving installation due to detached sensor electronics housing
- Backwards compatible with RD4 generation
- All advantages of the R-Series V



THE NEW **V** GENERATION

MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Tempsonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Tempsonics® position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

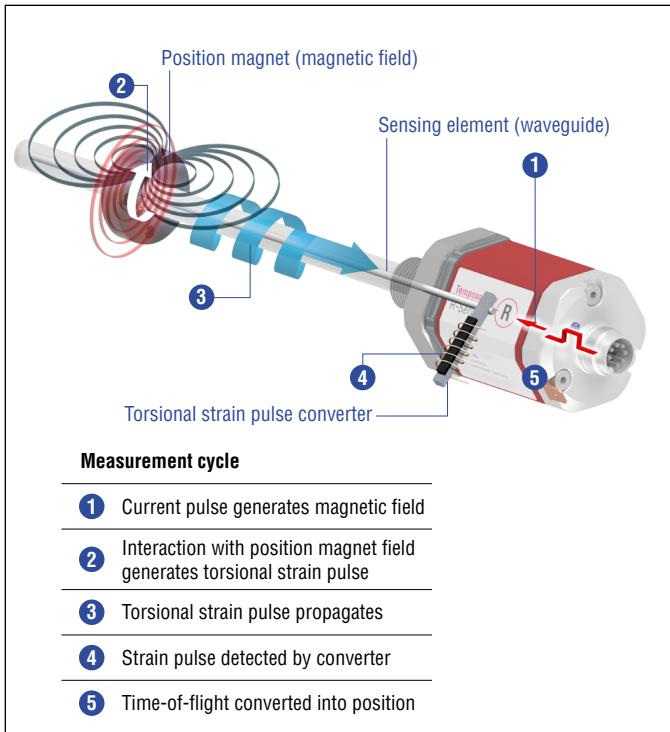
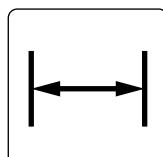


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

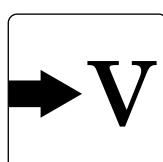
R-SERIES V RDV Analog

The Tempsonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The sensor RDV is the version of the R-Series V with a detached sensor electronics. The main advantages of the version RDV are:



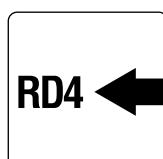
Space-saving installation

The detached sensor electronics allows space-saving installation of the compact measuring rod.



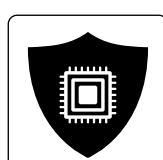
R-Series V platform

The detached sensor electronics is based on the R-Series V and offers all advantages of the innovative series.



Backwards compatible

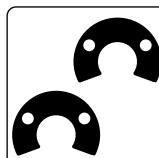
Mechanically and electrically, the sensors are backwards compatible with the RD4. This means that the sensor rod or the sensor electronics can be replaced without any problems.



Protection of the sensor electronics

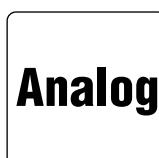
By separating the robust sensor rod from the complex evaluation electronics improved protection against process influences can be realized.

In addition the R-Series V Analog scores with the following features:



2 positions simultaneously

The R-Series V Analog can detect and report the position of up to 2 magnets simultaneously.



R-Series V Analog

With the R-Series V Analog you can configure the Analog output (current/voltage) that it fits best for your application and also adjust it on site with the smart assistant.

All settings under control with the smart assistant for the R-Series V
The TempoLink® smart assistant supports you in setup and diagnostics of the R-Series V.

For more information of the assistant please see the data sheet:

- TempoLink® smart assistant
(Document part number: [552070](#))



TECHNICAL DATA

Output												
Analog	Voltage: 0...10 / 10...0/-10...+10/+10...-10 VDC (min. controller load > 5 kΩ) Current: 4(0)...20/20...4(0) mA (min./max. load 0/500 Ω)											
Measured output variables	Position for one or two position magnets Position + speed (without direction) or velocity (with direction) for one position magnet Position for one position magnet + temperature inside the sensor electronics housing											
Measurement parameters												
Position measurement												
Null/Span adjustment	100 % of electrical stroke											
Resolution	16 bit (internal resolution 0.1 μm)											
Update time	Stroke length	≤ 200 mm	≤ 350 mm	≤ 1200 mm	≤ 2400 mm	≤ 4800 mm						
	Update time	0.25 ms	0.333 ms	0.5 ms	1.0 ms	2.0 ms						
Linearity deviation ^{1,2}	Stroke length	≤ 500 mm	> 500 mm									
	Linearity deviation	≤ ±50 μm	< ±0.01 % F.S.									
Repeatability	< ±0.001 % F.S. (minimum ±1 μm)											
Hysteresis	< 4 μm typical											
Temperature coefficient	< 30 ppm/K typical											
Velocity measurement												
Range	0.01...10 m/s or 1...400 in./s											
Deviation	≤ 0.05 %											
Resolution	16 bit (minimum 0.01 mm/s)											
Operating conditions												
Operating temperature	-40...+85 °C (-40...+185 °F)											
Humidity	90 % relative humidity, no condensation											
Ingress protection	Sensor electronics: IP67 (with correctly mounted housing and connectors) Measuring rod with connecting cable for side cable entry: IP65 Measuring rod with single wires and flat connector with bottom cable entry: IP30											
Shock test	100 g/11 ms, IEC standard 60068-2-27											
Vibration test	10 g/10...2000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)											
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The RDV sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011 under the condition of an EMC compliant installation ³											
Operating pressure	350 bar (5076 psi)/700 bar (10,153 psi) peak (at 10 × 1 min) for sensor rod											
Magnet movement velocity	Any											
Design/Material												
Sensor electronics housing	Aluminum (painted), zinc die cast											
Sensor rod with flange	Stainless steel 1.4301 (AISI 304)											
RoHS compliance	The used materials are compliant with the requirements of EU Directive 2011/65/EU and EU Regulation 2015/863 as well as UKSI 2022 No. 622											
Stroke length	25...2540 mm (1...100 in.) for pressure-fit flange »S« 25...5080 mm (1...200 in.) for all threaded flanges											

Technical data "Mechanical mounting" and "Electrical connection" on [page 4](#)

1/ With position magnet # 251 416-2

2/ For rod style »S« the linearity deviation can be higher in the first 30 mm (1.2 in.) of stroke length

3/ The cable between the sensor element and the sensor electronics housing must be mounted in an appropriately shielded environment

Tempsonics® R-Series V RDV Analog

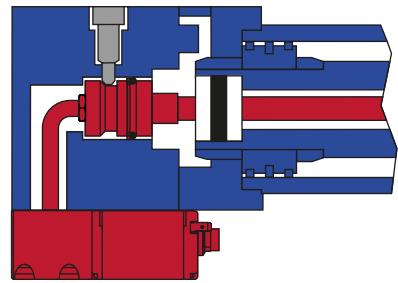
Data Sheet

Mechanical mounting	
Mounting position	Any
Mounting instruction	Please consult the technical drawings on page 5 , page 6 , page 7 and page 8 and the operation manual (document part number: 552063)
Electrical connection	
Connection type	1 × M16 male connector (6 pin), 1 × M12 male connector (5 pin) or cable outlet
Operating voltage	12...30 VDC ±20 % (9.6...36 VDC)
Power consumption	< 3.25 W
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	Up to -36 VDC
Oversupply protection	Up to 36 VDC

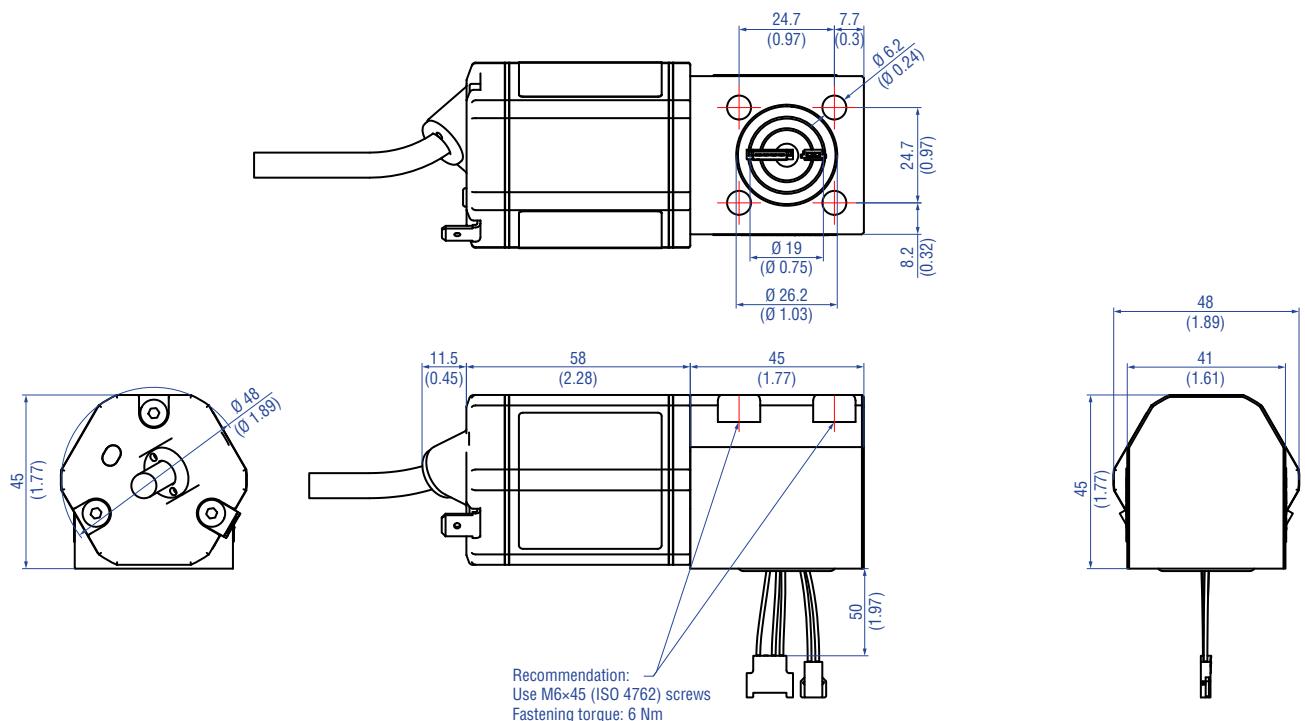
TECHNICAL DRAWING

RDV with bottom cable entry

- The connecting cables between the sensor electronics housing and the rod are routed into the interior via the bottom of the sensor electronics housing
- Rod and connecting cable are fully encapsulated and protected against external disturbances



RDV with bottom cable entry, example: EXX/GXX/LXX/UXX (angled cable outlet)

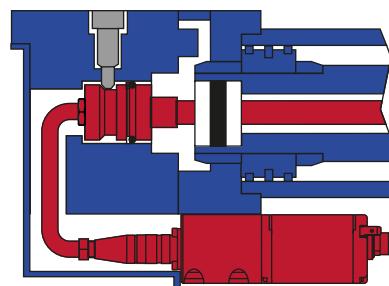


Controlling design dimensions are in millimeters and measurements in () are in inches

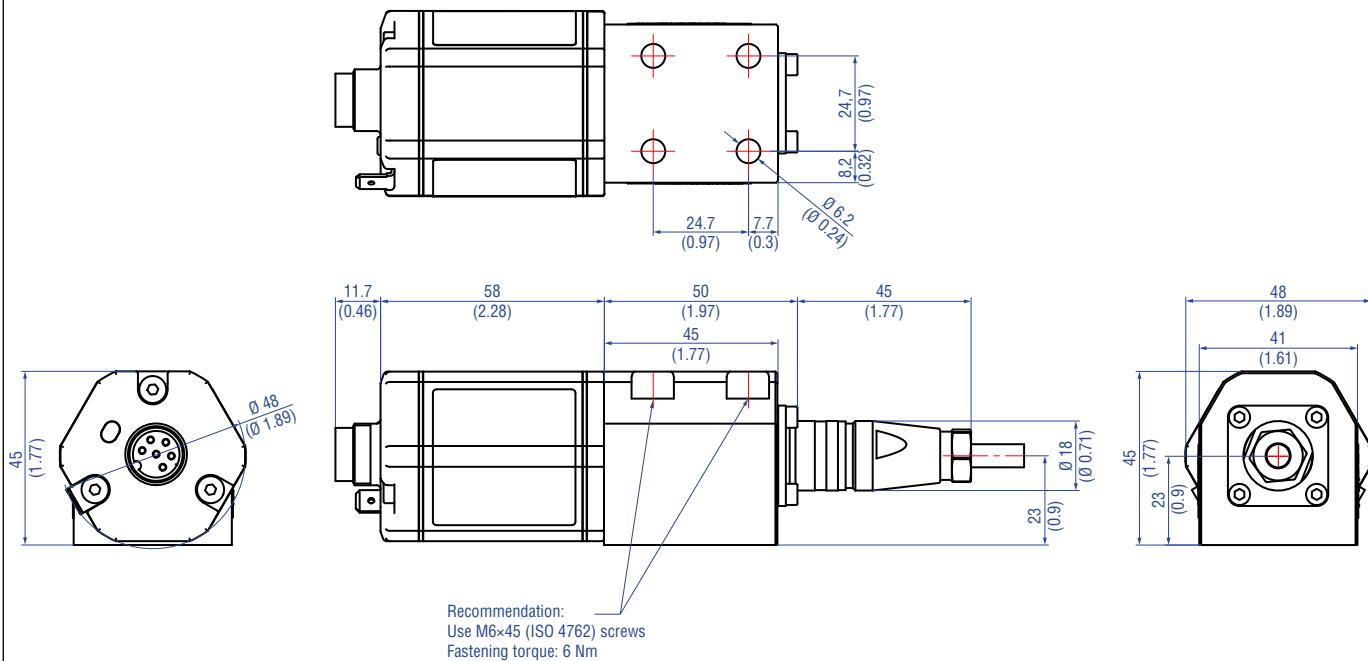
Fig. 2: Tempsonics® RDV sensor electronics housing with bottom cable entry

RDV with side connection

- The connecting cable between the sensor electronics housing and the rod is connected to the side of the sensor electronics housing
- Rod and connecting cable are sealed against dust and protected against water jets



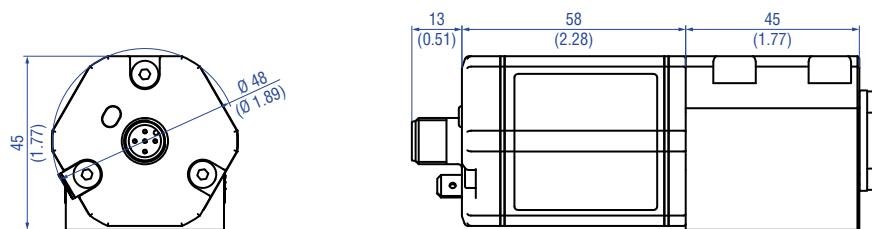
RDV with side cable entry, example: Connection type D60 (connector outlet)



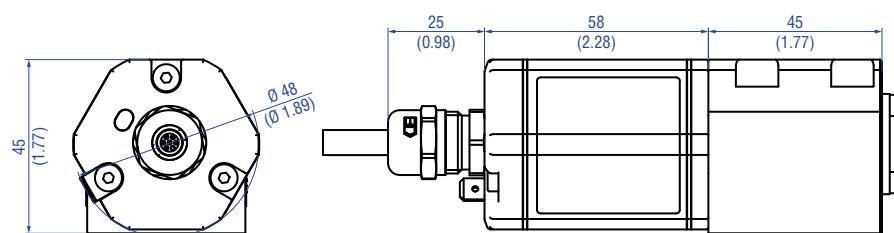
Controlling design dimensions are in millimeters and measurements in () are in inches

Fig. 3: Tempsonics® RDV sensor electronics housing with side cable entry

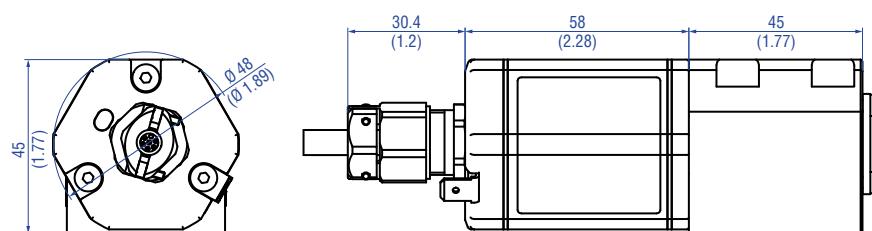
RDV with side cable entry, example: Connection type D34 (connector outlet)



RDV with side cable entry, example: Connection type HXX/RXX (straight cable outlet)



RDV with side cable entry, example: Connection type TXX (straight cable outlet)



Controlling design dimensions are in millimeters and measurements in () are in inches

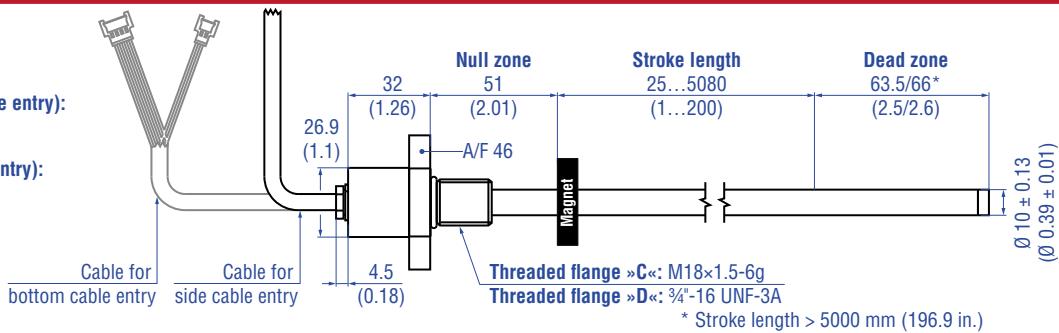
Fig. 4: Tempsonics® RDV sensor electronics housing with different outlet options

Tempsonics® R-Series V RDV Analog

Data Sheet

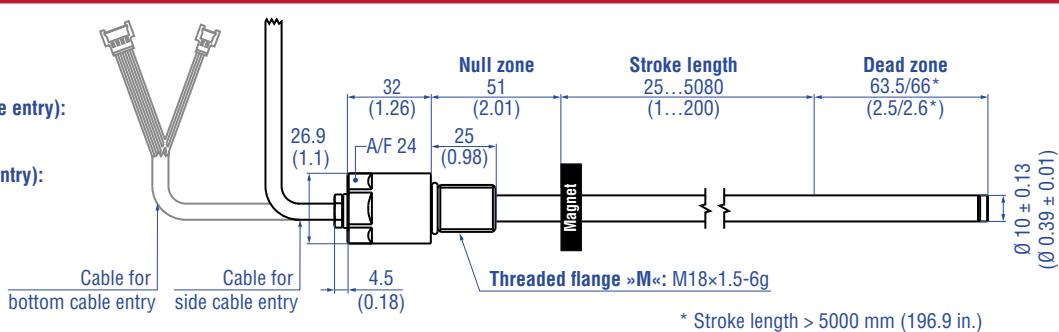
Threaded flange »C« & »D« (for bottom or side cable entry)

PUR cable:
 $\varnothing 6$ ($\varnothing 0.24$)
Bending radius:
 > 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



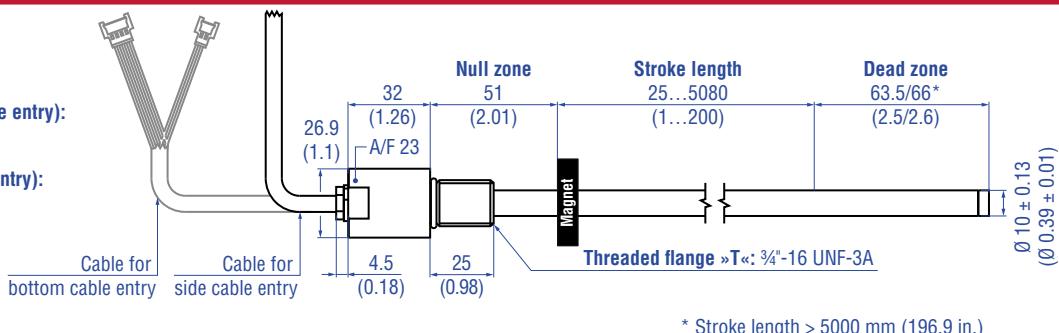
Threaded flange »M« (for bottom or side cable entry)

PUR cable:
 $\varnothing 6$ ($\varnothing 0.24$)
Bending radius:
 > 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



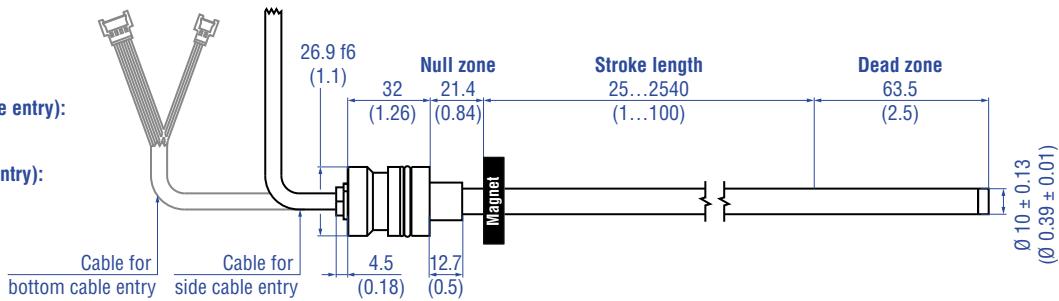
Threaded flange »T« (for bottom or side cable entry)

PUR cable:
 $\varnothing 6$ ($\varnothing 0.24$)
Bending radius:
 > 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



Pressure fit flange »S« (for bottom or side cable entry)

PUR cable:
 $\varnothing 6$ ($\varnothing 0.24$)
Bending radius:
 > 24 (> 0.94)
Cable length (bottom cable entry):
65/170/230/350
(2.6/6.7/9.1/13.8)
Cable length (side cable entry):
250/400/600
(9.8/15.7/23.6)



Controlling design dimensions are in millimeters and measurements in () are in inches

Fig. 5: Tempsonics® RDV flange types

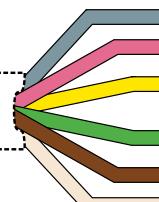
CONNECTOR WIRING

D34				
Signal + power supply				
M12 male connector	Output	Pin	Function	
	1	1	+12...30 VDC ($\pm 20\%$)	
		2	Position (magnet 1)	
	3	DC Ground (0 V)		
	2*	4	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing	
		5	Signal Ground	

Fig. 6: Connector wiring D34

D60				
Signal + power supply				
M16 male connector	Output	Pin	Function	
	1	1	Position (magnet 1)	
		2	Signal Ground	
	2*	3	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing	
		4	Signal Ground	
		5	+12...30 VDC ($\pm 20\%$)	
		6	DC Ground (0 V)	

Fig. 7: Connector wiring D60

HXX or LXX / RXX or EXX / TXX or GXX / UXX				
Signal + power supply				
Cable	Output	Color	Function	
	1	GY	Position (magnet 1)	
		PK	Signal Ground	
	2*	YE	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing	
		GN	Signal Ground	
		BN	+12...30 VDC ($\pm 20\%$)	
		WH	DC Ground (0 V)	

* order dependent

For cable type TXX, the extra red & blue wires are not used.

Fig. 8: Connector wiring cable outlet

Straight cable outlet			Cable type	Angled cable outlet
H	X	X	Part no. 530 052	PUR \rightarrow L X X Part no. 530 052
R	X	X	Part no. 530 032	PVC \rightarrow E X X Part no. 530 032
T	X	X	Part no. 530 112	FEP \rightarrow G X X Part no. 530 157

Fig. 9: Cable types assignment

FREQUENTLY ORDERED ACCESSORIES

– Additional options available in our [Accessories Catalog 551444](#)

Position magnets

U-magnet OD33 Part no. 251 416-2	Ring magnet OD33 Part no. 201 542-2	Ring magnet OD25.4 Part no. 400 533	Ring magnet OD17.4 Part no. 401 032
Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm ² Fastening torque for M4 screws: 1 Nm Operating temperature: –40...+105 °C (–40...+221 °F)	Material: PA ferrite GF20 Weight: Approx. 14 g Surface pressure: Max. 40 N/mm ² Fastening torque for M4 screws: 1 Nm Operating temperature: –40...+105 °C (–40...+221 °F)	Material: PA ferrite Weight: Approx. 10 g Surface pressure: Max. 40 N/mm ² Operating temperature: –40...+105 °C (–40...+221 °F)	Material: PA neobond Weight: Approx. 5 g Surface pressure: Max. 20 N/mm ² Operating temperature: –40...+105 °C (–40...+221 °F)

Magnet spacer

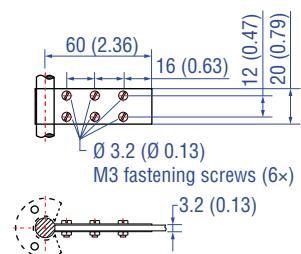
Magnet spacer Part no. 400 633	O-ring for threaded flange M18x1.5-6g Part no. 401 133	O-ring for threaded flange 3/4"-16 UNF-3A Part no. 560 315	O-ring for pressure fit flange Ø 26.9 mm Part no. 560 705
Material: Aluminum Weight: Approx. 5 g Surface pressure: Max. 20 N/mm ² Fastening torque for M4 screws: 1 Nm	Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: –40...+204 °C (–40...+400 °F)	Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: –40...+204 °C (–40...+400 °F)	Material: Nitrile rubber Operating temperature: –53...+107 °C (–65...+225 °F)

O-rings

Back-up ring for pressure fit flange Ø 26.9 mm Part no. 560 629	O-ring for mounting block with bottom entry Part no. 561 435	Hex jam nut M18x1.5-6g Part no. 500 018	Hex jam nut 3/4"-16 UNF-3A Part no. 500 015
Material: Polymyte Durometer: 90 Shore A	Material: FKM Durometer: 80± 5 Shore A Operating temperature: –15...+200 °C (5...+392 °F)	Material: Steel, zinc plated	Material: Steel, zinc plated

Controlling design dimensions are in millimeters and measurements in () are in inches

Mounting accessories

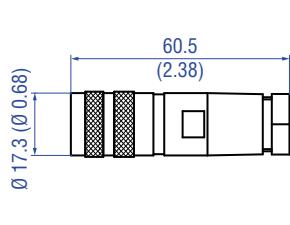
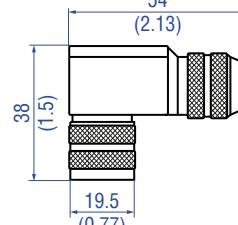
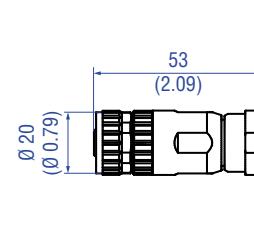
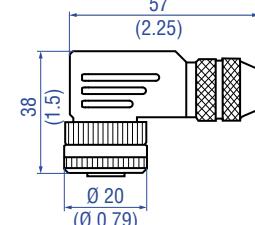


Fixing clip Part no. 561 481

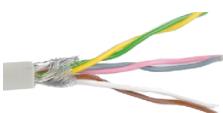
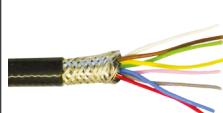
Application: Used to secure sensor rods (\varnothing 10 mm (\varnothing 0.39 in.)) when using an U-magnet or block magnet
Material: Brass, non-magnetic

Controlling design dimensions are in millimeters and measurements in () are in inches

Cable connectors*

			
M16 female connector (6 pin), straight Part no. 370 423	M16 female connector (6 pin), angled Part no. 370 460	M12 A-coded female connector (4 pin/5 pin), straight Part no. 370 677	M12 A-coded female connector (5 pin), angled Part no. 370 678
Material: Zinc nickel plated Termination: Solder Cable Ø: 6...8 mm (0.24...0.31 in.) Operating temperature: -40...+100 °C (-40...+212 °F) Ingress protection: IP65/IP67 (correctly fitted) Fastening torque: 0.6 Nm	Material: Zinc nickel plated Termination: Solder Cable Ø: 6...8 mm (0.24...0.31 in.) Wire: 0.75 mm ² (20 AWG) Operating temperature: -40...+95 °C (-40...+203 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.6 Nm	Material: GD-Zn, Ni Termination: Screw Contact insert: CuZn Cable Ø: 4...8 mm (0.16...0.31 in.) Wire: 1.5 mm ² Operating temperature: -30...+85 °C (-22...+185 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.6 Nm	Material: GD-Zn, Ni Termination: Screw; max. 0.75 mm ² Contact insert: CuZn Cable Ø: 5...8 mm (0.2...0.31 in.) Wire: 0.75 mm ² (18 AWG) Operating temperature: -25...+85 °C (-13...+185 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.4 Nm

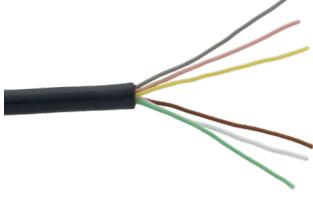
Cables

			
PVC cable Part no. 530 032	PUR cable Part no. 530 052	FEP cable Part no. 530 112	FEP cable Part no. 530 157
Material: PVC jacket; gray Features: Twisted pair, shielded, flexible Cable Ø: 6 mm (0.23 in.) Cross section: 3 x 2 x 0.14 mm ² Bending radius: 10 x D (fixed installation) Operating temperature: -40...+105 °C (-40...+221 °F)	Material: PUR jacket; orange Features: Twisted pair, shielded, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant Cable Ø: 6.4 mm (0.25 in.) Cross section: 3 x 2 x 0.25 mm ² Bending radius: 5 x D (fixed installation) Operating temperature: -30...+80 °C (-22...+176 °F)	Material: FEP jacket; black Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil & acid resistant Cable Ø: 7.6 mm (0.3 in.) Cross section: 4 x 2 x 0.25 mm ² Bending radius: 8 – 10 x D (fixed installation) Operating temperature: -100...+180 °C (-148...+356 °F)	Material: FEP jacket; black Features: Twisted pair, shielded Cable Ø: 6.7 mm (0.26 in.) Cross section: 3 x 2 x 0.14 mm ² Operating temperature: -40...+180 °C (-40...+356 °F)

*/ Follow the manufacturer's mounting instructions

Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

Controlling design dimensions are in millimeters and measurements in () are in inches

Cables	Cable sets	
		
Programming tools		
		
Hand programmer for analog output Part no. 253 124	Cabinet programmer for analog output Part no. 253 408	TempoLink® kit for Tempsonics® R-Series V Part no. TL-1-0-AD60 (for D60) Part no. TL-1-0-AS00 (for cable outlet) Part no. TL-1-0-AD34 (for D34)
Easy teach-in-setups of stroke length and direction on desired zero/span positions. For sensors with 1 magnet.	Features snap-in mounting on standard DIN rail (35 mm). This programmer can be permanently mounted in a control cabinet and includes a program/run switch. For sensors with 1 magnet.	<ul style="list-style-type: none"> • Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool • Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m) • User friendly interface for mobile devices and desktop computers • See data sheet "TempoLink® smart assistant" (document part no.: 552070) for further information

Controlling design dimensions are in millimeters and measurements in () are in inches
Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

Extension cables M12



PVC cable with M12 female connector (6 pin), straight - pigtail

PVC cable (part no. 530 032) with M12 female connector, straight (part no. 370 677)

Order code:
K2-A-370677-xxxxyy-530032-0
(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



PUR cable with M12 female connector (6 pin), straight - pigtail

PUR cable (part no. 530 052) with M12 female connector, straight (part no. 370 677)

Order code:
K2-A-370677-xxxxyy-530052-0
(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



FEP cable with M12 female connector (6 pin), straight - pigtail

FEP cable (part no. 530 112) with M12 female connector, straight (part no. 370 677)

Order code:
K2-A-370677-xxxxyy-530112-0
(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")

Extension cables M16



PVC cable with M16 female connector (6 pin), straight - pigtail

PVC cable (part no. 530 032) with M16 female connector, straight (part no. 370 423)



PUR cable with M16 female connector (6 pin), straight - pigtail

PUR cable (part no. 530 052) with M16 female connector, straight (part no. 370 423)

Order code:
K2-A-370423-xxxxyy-530052-0
(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



FEP cable with M16 female connector (6 pin), straight - pigtail

FEP cable (part no. 530 112) with M16 female connector, straight (part no. 370 423)

Order code:
K2-A-370423-xxxxyy-530112-0
(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")

Notice for extension cables M12/M16

Standard cable lengths		
Meters	Feet	Code
1.5	5	0150
2	6.6	0200
4.6	15	0460
5	16.4	0500
7.6	25	0760
10	32.8	1000
15.2	50	1520

For additional extension cables reference the accessory catalog for industrial sensors (document part no.: [551444](#)).

Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

ORDER CODE

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
R	D	V													1							

a

b

c

d

e

f

16	17	18	19	20	21	22	23
g	h	i	j	k	l	l	l

optional

a	Design
R	D V Detached sensor electronics "Classic"

e	Number of magnets
0	X 01...02 Position(s) (1...2 magnet(s))

b	Design
C	Threaded flange M18×1.5-6g (A/F 46)
D	Threaded flange 3/4"-16 UNF-3A (A/F 46)
M	Threaded flange M18×1.5-6g (A/F 24)
S	Pressure fit flange Ø 26.9 mm f6
T	Threaded flange 3/4"-16 UNF-3A (A/F 23)

f	Connection type
Connector	
D 3 4	M12 male connector (5 pin)
D 6 0	M16 male connector (6 pin)

c	Mechanical options
For side cable entry	
A	PUR cable with M16 connector, 250 mm length
B	PUR cable with M16 connector, 400 mm length
C	PUR cable with M16 connector, 600 mm length
For bottom cable entry	
2	Single wires with flat connector, 65 mm length
4	Single wires with flat connector, 170 mm length
5	Single wires with flat connector, 230 mm length
6	Single wires with flat connector, 350 mm length

Angled cable outlet	
E X X	XX m/ft. PVC cable (part no. 530 032) E01...E30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications
G X X	XX m/ft. FEP cable (part no. 530 157) G01...G30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications
L X X	XX m/ft. PUR cable (part no. 530 052) L01...L30 (1...30 m/3...99 ft.) (Note the temperature range of the cable!) See "Frequently ordered accessories" for cable specifications
U X X	XX m/ft. Silicone cable (part no. 530 176) U01...U30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications

d	Stroke length
X X X X M	Flange »S«: 0025...2540 mm Flange »C«, »D«, »M«, »T«: 0025...5080 mm
Stroke length (mm)	Ordering steps
25... 500 mm	5 mm
500... 750 mm	10 mm
750...1000 mm	25 mm
1000...2500 mm	50 mm
2500...5080 mm	100 mm
X X X X U	Flange »S«: 001.0...100.0 in. Flange »C«, »D«, »M«, »T«: 001.0...200.0 in.
Stroke length (in.)	Ordering steps
1... 20 in.	0.2 in.
20... 30 in.	0.4 in.
30... 40 in.	1.0 in.
40...100 in.	2.0 in.
100...200 in.	4.0 in.

Non standard stroke lengths are available;
must be encoded in 5 mm/0.1 in. increments

Straight cable outlet	
H X X	XX m/ft. PUR cable (part no. 530 052) H01...H30 (1...30 m/3...99 ft.) (Note the temperature range of the cable!) See "Frequently ordered accessories" for cable specifications
R X X	XX m/ft. PVC cable (part no. 530 032) R01...R30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications
T X X	XX m/ft. FEP cable (part no. 530 112) T01...T30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications

Encode in meters if using metric stroke length.
Encode in feet if using US customary stroke length.

g	System
1	Standard
h	Output
A	Current
V	Voltage

i	Function
1	Position (1 or 2 magnets/outputs)
2	Position and speed (1 magnet and 2 outputs) Specify the maximum speed value in section i
3	Position and velocity (1 magnet and 2 outputs) Specify the maximum velocity value in section i
4	Position and reverse position (1 magnet and 2 outputs)
5	Position and temperature inside the sensor electronics housing (1 magnet and 2 outputs)
6	Differential (2 magnets and 1 output)

j	Options
0	Standard
3	Over range output mode

k	Output range
0	0...10 VDC or 4...20 mA
1	10...0 VDC or 20...4 mA
2	-10...+10 VDC or 0...20 mA
3	+10...-10 VDC or 20...0 mA
V	0...10 VDC for position, -10...+10 VDC for velocity

l	Max. speed or velocity value
(optional: use when i "Function" is 2 or 3)	
<input type="checkbox"/>	For metric stroke lengths encode speed or velocity in m/s for the values 0.01 to 9.99 m/s (001...999)
<input type="checkbox"/>	For US customary stroke lengths encode speed or velocity in inches/s for the values 1 to 400 in./s (001...400)

To get a speed or velocity output of 0.025 m/s or 10 m/s for the R-Series V Analog, enter code (00E) for 0.025 m/s or (A00) for 10.0 m/s in the order code.

DELIVERY



RDV-C/-D/-M/-T:

Sensor, O-ring

RDV-S:

Sensor, O-ring, back-up ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at:

www.temposonics.com

NOTICE	
<ul style="list-style-type: none"> Specify the number of magnets for your application and order the magnets separately. The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.). Use magnets of the same type for differential/multi-position measurement. 	

GLOSSARY

A

Analog output

For a sensor with analog output, the measured value is output as an analog voltage signal or current signal.

D

Differential

For differential measurement, the distance between the two position magnets is output as a value.
(→ multi-position measurement)

M

Max. speed or velocity value

For speed or velocity, the output value generated is scaled based on the maximum speed or velocity value indicated in the order code.

Measuring direction

- Forward: Values increasing from sensor electronics housing to rod end/profile end
- Reverse: Values decreasing from sensor electronics housing to rod end/profile end

Multi-position measurement

During the measurement cycle, the positions of every magnet on the sensor are simultaneously reported. The velocity or speed is continuously calculated based on these changing position values as the magnets are moved.

O

Over range output mode

When enabled this mode allows the position output values to continue to increase or decrease when the magnet travels beyond the active stroke range.

R

Resolution

The sensor precisely measures time to provide the position measurement. For the analog output the measured time value is converted into an analog voltage signal or current signal using a high-performance Digital to Analog Converter (DAC) having 16 bits of resolution.

S

Speed

The output value for speed indicates how fast the position magnet is being moved, independent of the measuring direction. (→ Velocity)

T

Temperature inside the sensor electronics housing

The temperature inside the sensor electronics housing is reported as an analog voltage signal or current signal. For each output range, the 0 % output value has the factory default setpoint at -40 °C, and the 100 % output value has the default setpoint at +100 °C.
Note: A dedicated temperature chip is used for the output signal and its values may vary from those reported on the TempoLink® application screen.

V

Velocity

The output value for velocity indicates how fast the position magnet is being moved, and in which direction. (→ Speed)



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